

Implementation of variable segments to model the arterial system using electromechanical analogy

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The article deals with the design of an electrical model of variable segments of a non-symmetrical tree of small arteries. This model can be used to simulate the blood pressure and flow. Peripheral arterial resistance changes are modelled by an exponentially dependent resistor. By modulating the capacitor value, we can model the arterial wall properties which depend on the arterial pressure. Simulations are performed in which vasoconstriction and vasodilation were modelled by varying the transmural pressure. As a result, we can observe the changes in the blood pressure for each arterial generation.

Key words: arterial system, electromechanical analogy, modelling and simulations, small arteries, transmural pressure

1 Introduction

When compared with large arteries, small arteries and arterioles have similar physical properties from the viewpoint of blood pressure and blood flow. The basic difference rests in their spatial organization. The mother vessel can bifurcate to two daughter vessels. This branching pattern can be observed through the whole arterial tree. In addition, we find the difference in the vessel length-to-diameter ratio. This ratio is relatively high in the case of large arteries and, on the other hand, for small arteries this ratio is small as their lengths and diameters are comparable [1, 2]. We used a model of the arterial tree with distributed parameters which is based on the use of electromechanical analogy. Consequently, we used the transmission line theory and in this way, it is possible to divide the model of the arterial tree to appropriately long segments with specific geometrical and mechanical properties. Spatial organization was adopted from [3]. The single segment is shown in Fig. 1, where resistance R corresponds to blood viscosity, inductance L corresponds to blood density and capacitance C is connected to the arterial wall elasticity [3–6].

2 Materials

There are many regulation mechanisms of the arterial system. Branching of small arteries offers an extension of this system by implementing such a regulation mechanism which is connected to the changes of arterial radii. It is peripheral vascular resistance regulation which can be implemented to the model of the arterial system by modification of the original small arterial segment, see Fig. 1. The modification is based on the elements with variable

parameters. These parameters change with alternation of the internal and external stimuli. The arterial pressure and flow vary depending on the arterial radius, and the arterial wall properties such as arterial elasticity are sensitive to the arterial radius changes. Therefore, it is needed to modify the original arterial segment to a segment with variable resistor R_1 and variable capacitor C . By modulating the resistor value R_1 one can model the peripheral arterial resistance changes, while by alternating the capacitance C relates to the arterial wall properties which are a function of arterial pressure.

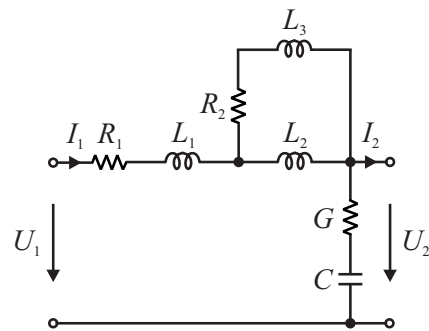


Fig. 1. Arterial segment transformed to an electrical circuit using electromechanical analogy

By using the Ohm law we get the equation for the voltage across capacitor C

$$\frac{du_C(t)}{dt} = \frac{1}{C(u(t))} i(t). \quad (1)$$

But for our implementation, the integral form of (1) is preferable

$$u_C(t) = \int \frac{1}{C(u(t))} i(t) dt \quad (2)$$

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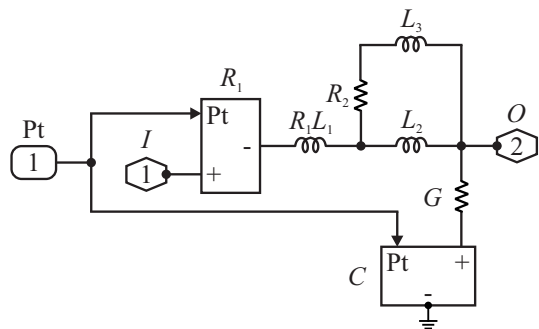


Fig. 2. Arterial segment with variable elements implemented in SIMULINK

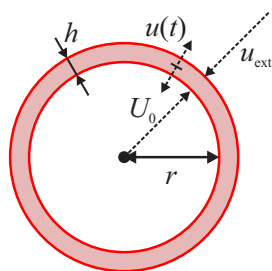


Fig. 3. Pressures acting on the arterial wall

where $i(t)$ is the electrical current flowing through the transversal branch of the modelled arterial segment and $u_C(t)$ is the electrical voltage across capacitor C (see Fig. 1 or its modified version Fig. 2).

In our implementation, we use voltage $u(t)$ which represents the transmural pressure from the point of view of the electromechanical analogy. Transmural pressure $u(t)$ is defined by subtraction of the mean pressure U_0 inside the artery and the external pressure $u_{ext}(t)$ caused by some regulation mechanism or striated muscle contraction. These pressures have an antagonistic effect and their resultant is the transmural pressure which relates to the transversal dilatation or constriction of the selected artery, see Fig. 3,

$$u(t) = U_0 - u_{ext}(t). \quad (3)$$

By modelling the transmural pressure changes we can simulate the arterial constriction ($u(t) < 0$) or arterial dilatation, where $u(t) > 0$. The values of elements R_1 and C vary depending on the voltage $u(t)$. We can define a change in capacitance C

$$C(u) = C_0 e^{-\alpha_C \frac{u(t)}{U_0}} \quad (4)$$

where C_0 is the initial value of capacitance when we assume the artery in the initial condition (internal and external pressures equal and it follows that $u(t) = 0$). Using the parameter α_C it is possible to change the curve slope characterizing the capacitance value in dependence on the transmural pressure changes. In this way we can

model the arterial wall response to pressure changes. The voltage across capacitor C is

$$u_C(t) = \frac{1}{C_0} \int i(t) e^{\alpha_C \frac{u(t)}{U_0}} dt = \frac{1}{C_0} \int i(t) e^{\alpha_C \left(1 - \frac{u_{ext}(t)}{U_0}\right)} dt. \quad (5)$$

We can use an analog derivation also to model the variable resistor R_1 . When the artery constricts, the R_1 value increases and vice versa, so the voltage across the resistor is

$$u_{R_1}(t) = R_1(u(t)) i_1(t) \quad (6)$$

where $i_1(t)$ represents the electrical current flowing through resistor R_1 whose value is defined similar to (6)

$$R_1 = R_0 e^{-\alpha_R \frac{u(t)}{U_0}} \quad (7)$$

where R_0 is the value of the peripheral vascular resistance of the selected arterial segment in the initial state (internal and external pressures equal and it follows that $u(t) = 0$). Using the parameter α_R it is possible to change the curve slope characterizing the resistance value in dependence on the transmural pressure changes and in this way we can model the arterial wall response to the pressure changes. The voltage across resistor R_1 is expressed as

$$u_{R_1}(t) = R_0 e^{-\alpha_R \frac{u(t)}{U_0}} i_1(t) \quad (8)$$

Figure 4 shows the capacitance and resistance value changes in dependence on the different values of the transmural pressure. Dilating the artery, the fibres which the artery consists of are stretched and in this way the artery becomes more rigid. Its compliance or elasticity decreases and its overall capacitance and resistance also decrease. By constriction of the artery, the overall resistance increases and by dilatation the resistance decreases. Variable segment according to Fig. 4 are placed in the tree of the small arteries in the fifth generation on the left side, see [7].

3 Results

Functionality of the variable element segments was verified in the MATLAB-SIMULINK programming environment. Variable segments were placed in the 4th and 5th generations of the modelled arterial tree. We measured the voltage at the place of each bifurcation until the 7th generation in the β side of the tree (see [7] for topology details. During simulation, the transmural pressure was changed from -100 to 100 mmHg by using

$$u(t) = U_m \sin(2\pi ft) \quad (9)$$

where U_m represents the amplitude of the signal, f is oscillation frequency of the transmural pressure set to 0.1 Hz and t is time in seconds.

By using (8) it is possible to simulate the changes in the small arterial tree. As discussed in the text above,

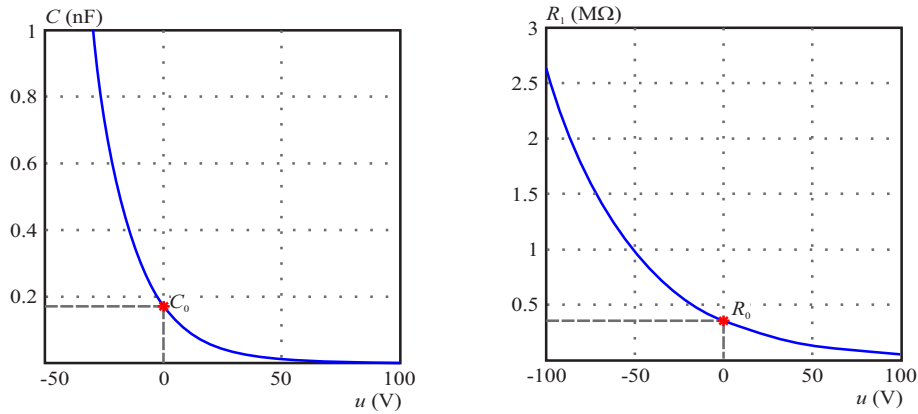


Fig. 4. Capacitance C (left) and resistance R_1 (right) changes in dependence on the transmural pressure

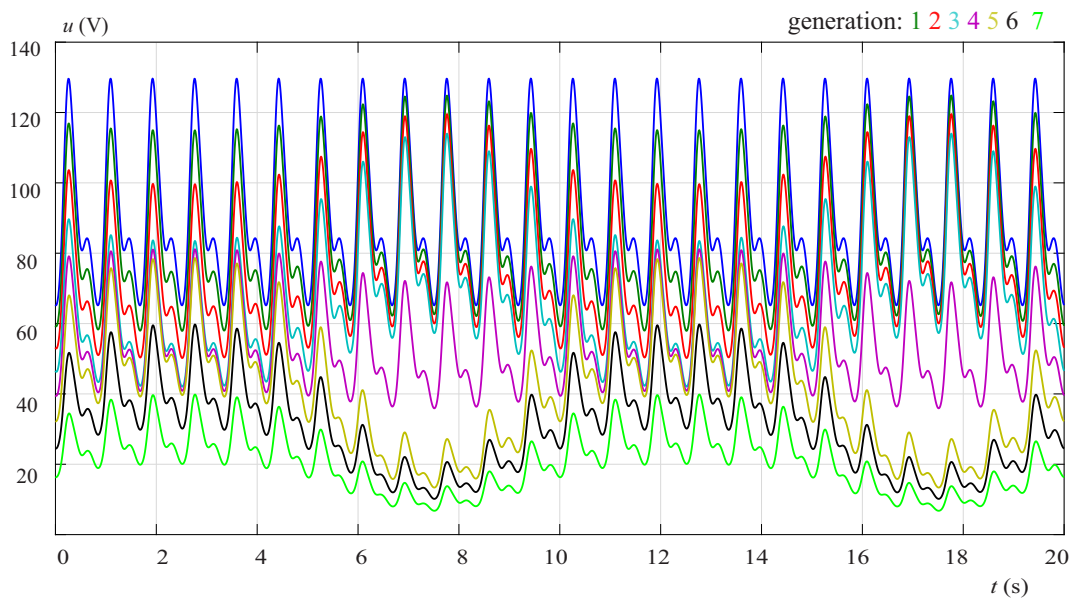


Fig. 5. Simulation results of transmural pressure changes and their impact on the blood pressure in small arterial segments

constriction occurs at $u(t) < 0$. Vasoconstriction is visible, *eg*, from the 5th to the 10th second of the simulated arterial pressure in the appropriate generations, see Fig. 5. We can see a blood pressure drop by the increased peripheral resistance simulated by resistor R_1 . We can observe the impact of the arterial elasticity changes modelled by capacitor C at the 8th second of the record. The dirotic notch of the pressure curve is flatter and this phenomenon is caused by capacitance changes which have an impact on the cutoff frequency of the selected segment. By simulation of the variable elements we can observe the pressure and flow changes in single small arterial segments in appropriate generations.

4 Conclusions

A tree of small arteries was created per physiological observations described in [8–12]. Placing of variable elements into single arterial segments leads to pressure (voltage) changes in the small arterial tree. The presented

model can serve for examination and observation of the pressure and flow changes related to certain regulation mechanisms causing vasomotion *etc*. There is a possibility to modulate the arterial dilatation or constriction easily by changing the parameters of exponential functions which describe the behaviour of the variable elements. Modelling of the vascular system by electromechanical analogies can lead to a better understanding of the processes which occur in arteries. Also, it could be possible to evaluate the degree of pathological changes in the arterial system by using appropriate measurement methods (*eg*, photoplethysmography) [12] and by reverse comparisons of the measured and simulated data. In this way, malformations such as arterial stenosis or aneurysm could be deeply studied.

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