

# **Compact log-periodic microstrip DGS filters with high figure-of-merit**

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This contribution is an extended in-depth study of our previously initial research work about the compact Log-periodic microstrip DGS lowpass filters. The improved filters proposed use a log-periodic zig-zag structure defected on the ground plane under a compensated microstrip line for microwave filter applications. More importantly, a comprehensive index called figure-of-merit (FoM) is introduced in this paper to characterize the achieved performance of this kind of filters. Results show that high FoMs can be realized for this contribution. The developed filters B and C have dimensions  $30.307 \text{ mm} \times 31.17 \text{ mm}$ and 22.35 mm  $\times$  31.524 mm, while the achieved FoMs for the two demonstrators are approximately 3.5×10<sup>4</sup> and 3.1×10<sup>4</sup>, respectively.

Keywords: microwave filter, log-periodic, defected ground structure (DGS), suppression band, figure-of-merit (FoM)

#### **1 Introduction**

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Microwave filters can be used to separate or combine different frequency channels for microwave engineering applications. They are indispensable in many RF/microwave systems. This has been demonstrated by the recent increase in various filter studies ranging from lowpass filters (LPFs) to bandstop filters [1, 2]. The introduction of geometrical patterns etched off on the back-side metallic ground plane of microstrip-based filter designs has shown attractive results in application to the microwave and RF domains [3, 4]. These etched shapes can manipulate the frequency responses, yielding a class of microwave filters referred to as defected ground structure (DGS) filters. The DGS can reject frequency bands because of the slow-wave effect that leads to increasing the effective inductance and capacitance of the microwave transmission line. This design technique is a good choice to achieve low-profile compact filters without compromising on the electric performance.

In [4], authors presented a flexible microstrip LPF fabricated on a polyimide film substrate. The proposed filter consists of ten cascaded asymmetrical Pi-shaped DGS resonators. This filter has a low insertion loss of less than 1.9 dB under the cut-off frequency of 2.2 GHz, and a wide stopband from 2.7 to 12 GHz with a rejection level over 50 dB. It is characterized by a sharp transition band, an ultra-wide stopband with a high rejection level compared with previously reported microstrip LPFs with symmetrical or asymmetrical DGSs. In [5], a hairpin DGS LPF with a simple architecture that can present attenuation and reflection poles near the cut-off

frequency was reported, where a wide stopband with a high suppression level was demonstrated. In [6], a fivestage dumbbell-shaped DGS was developed for microwave differential bandpass filter applications, where the presented equivalent lumped LC model predicated the in-band response well. In [7], log-periodic zig-zag DGS with simple architecture was studied for wide suppression band LPF applications.

On the other hand, small estate-size and highperformance LPFs having wide stopband, good return loss and low insertion loss are in high demand for RF/microwave engineering. This is due to the ability of such filters to inhibit wideband noise and spurious signals which is important in wireless systems [8, 9]. In [8], asymmetric Koch fractal Pi-shaped DGS LPFs with single and two cascaded resonators were presented. The reported LPFs have wide stopbands and sharp transition bands. For a single unit cell, it can achieve a passband up to 1.9 GHz with an insertion loss of less than 0.5 dB, and a stopband from 2 GHz to 8 GHz with an attenuation level over 12 dB. In [10], the authors' simulation studied a compact ultra-wideband filter having a wide stopband using a modified multi-mode resonator-based structure in combination with DGS based LPF configuration. With meandering high impedance line loading to a strip to form the defected ground, the study reported in [11] shows that a wide stopband LPF can be developed by further using stub loading and spur line on the microstrip line. In general, microwave filters with simple architecture without compromising stringent requirements are much desired in modern RF/microwave systems.

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Based on our previous study, the log-periodic zig-zag based DGS is further discussed in detail in this paper. The developed filters feature a wide stopband and low insertion loss within the passband as well as a sharp transition between the passband and stopband. To effectively characterize the achieved performance of such kinds of filters, a comprehensive index called figure-of-merit (FoM) is studied in this work. Prototype filters are developed, fabricated, and demonstrated. Simulation and measurement results are presented and compared. They show good agreement and hence, high FoMs can be achieved for the proposed filters.

#### **2 Analyses on the slotline base DGS**

The log-periodic zig-zag DGS is based on the slotline, the same as studied in [7]. The idea arose from the principle of log-periodic antenna design. It is known that the log-periodic antenna is a frequency-independent antenna composed of resonant elements. Here the slots are etched on the ground plane of a microwave substrate under a compensated microstrip line. The substrate used has a relative permittivity of *εr*=9.6 and a thickness of *h*=0.8mm.



**Fig. 1.** The studied log-periodic zig-zag DGS etched on the ground plane

For the general case of the log-periodic antenna, the resonant elements are parallel to each other but for the proposed log-periodic DGS structure the resonant elements were etched on the ground plane and have been arranged in a zig-zag fashion (slanted resonant elements) with a small gap of 'g' between the tip of each vertex of the zig-zag resonant elements, as shown in Fig. 1 and the same as in our previous study in [7].

Also, referred to the horizontal axis shown in Fig. 1 (corresponding to the central line, which is also the direction of the positioned microstrip line), the height from the vertex of each zig-zag to the central line is  $h_n$ , for the  $n^{\text{th}}$  slanted slot. Similarly, it is marked as  $h_{n+1}$  for the  $(n+1)$ <sup>th</sup> slot. The spacing between two adjacent apexes is  $p_n$  related to the  $n^{\text{th}}$  slot. The two parameters are called geometric ratio or scale factor which can be given by the height ratio described in (1),

$$
h_{n+1} = \frac{h_n}{\tau_h} = \dots = \frac{h_1}{\tau_h^n}
$$
 (1)

for the spacing ratio,

$$
p_{n+1} = \frac{p_n}{\tau_p} = \dots = \frac{p_1}{\tau_p^n}.
$$
 (2)

Here, both ratios of  $\tau_h$  and  $\tau_p$  are less than 1. To separate the slots between two adjacent apexes of the zig-zag, a small gap that is denoted as '*g*' is introduced at the tip of each apex as shown in Fig. 1.

The height  $h_n$  and spacing  $p_n$  co-determine the length of the related slot and further determine its resonance. On the other hand, the zig-zag fashion also leads to a half vertex angle  $\alpha_n$  and a horizontal angle  $\beta_n$  related to the  $n^{\text{th}}$  slanted slot and so are the  $\alpha_{n+1}$  and  $\beta_{n+1}$  for the adjacent  $(n+1)$ <sup>th</sup> slot. Different from the previous study in [7], we will detail these parameters here. Referring to Fig. 1, it is observed that for the  $n<sup>th</sup>$  slot

$$
\tan \alpha_n = \frac{\tau_p}{1 + \tau_h} \left(\frac{\tau_h}{\tau_p}\right)^n \frac{p_1}{h_1} \tag{3}
$$

and

$$
\tan \beta_n = \frac{1 - \tau_h^2}{\left(1 + \tau_p\right) \tau_h} \left(\frac{\tau_p}{\tau_h}\right)^n \frac{h_1}{p_1},\tag{4}
$$

while for the  $(n+1)$ <sup>th</sup> slot

$$
\tan \alpha_{n+1} = \frac{\tau_p}{1 + \tau_h} \left(\frac{\tau_h}{\tau_p}\right)^{n+1} \frac{p_1}{h_1} \tag{5}
$$

and

$$
\tan \beta_{n+1} = \frac{1 - \tau_h^2}{\left(1 + \tau_p\right) \tau_h} \left(\frac{\tau_p}{\tau_h}\right)^{n+1} \frac{h_1}{p_1} \,. \tag{6}
$$

All these result in

$$
\frac{1-\tau_h}{1+\tau_p} \cdot \frac{\tau_p}{\tau_h} = \tan \alpha_n \tan \beta_n = \tan \alpha_{n+1} \tan \beta_{n+1} \,. \tag{7}
$$

To this end, Eqn. (7) presents the relationship between the vertex angles  $\alpha_n$  and horizontal angles  $\beta_n$  as well as the ratios of  $\tau_h$  and  $\tau_p$ . Now, if one sets the height ratio and the spacing ratio to be  $\tau_h = \tau_p = \tau$ , the above results will become

$$
\cdots = \alpha_n = \alpha_{n+1} = \cdots = \alpha \tag{8}
$$

for all vertex angles of the slot array and

$$
\cdots = \beta_n = \beta_{n+1} = \cdots = \beta \tag{9}
$$

for all horizontal angles of the slot array while

$$
\tau = \frac{1 - \tan \alpha \tan \beta}{1 + \tan \alpha \tan \beta} \tag{10}
$$

On the other hand, if we set  $\alpha = \beta$ , Eqn. (7) would lead to

$$
\alpha = \beta = \tan^{-1} \sqrt{\frac{1 - \tau_h}{1 + \tau_p} \cdot \frac{\tau_p}{\tau_h}}.
$$
 (11)

If one sets both  $\tau_h = \tau_p = \tau$  and  $\alpha = \beta$ , Eqn. (7) would become a very simple style as given by

$$
\tau = \cos 2\alpha = \cos 2\beta \tag{12}
$$

In practice, both angles of  $\alpha$  and  $\beta$  are in the range of 0 to 90 degrees, so *τ* is less than one as described earlier. Based on the above discussions, the geometric parameters of this kind of DGS can be determined and so is the filter design as presented below.

## **3 Developing microstrip lowpass filters based on the studied DGS**

The above discussions are further explored for application to the DGS filter designs. Here we first examine the previous studies presented in [7]. Based on the optimal scheme using full-wave electromagnetic (EM) numerical simulations, the final parameters are given by  $h_{10}=16$  mm with  $\tau$  (= $\tau_p=\tau_h$ )=0.835, leading to  $p_1$ =1.999 mm and  $h_1$ =3.164 mm. Correspondingly, the angles are  $\alpha=16^{\circ}$  and  $\beta=17.38^{\circ}$  from the layout measurements, while the results from Eqns. (3) and (4) are  $\alpha$ =16.04° and  $\beta$ =17.37°, showing good agreements. The filter has a measured 3 dB cut-off frequency of 1.96 GHz and a layout footprint of  $40.653 \times 29.546$  mm<sup>2</sup>. We marked this filter as prototype Filter A for reference.

# *3.1 Prototype filter B: Compact footprint and wide stopband design*

Now, we are devoting to the compact design, except for the wide suppression band, for this kind of filters. Also, for simplicity, the ratios are set as  $\tau_p = \tau_h = \tau$ , and referring to Filter A, it is approximately 0.85. To achieve compactness, the longitudinal dimension should be compressed, corresponding to reducing the periodicity length  $p_i$ . On the other hand, to maintain the same suppression band, the height dimension should be enlarged because of the decreased  $p_i$  to hold a similar resonance. Thus, the corresponding height *h<sup>i</sup>* is increased here. To this end, we directly set the first periodicity length and the height as  $p_1=1.6$  mm and  $h_1=3.8$  mm, referring to the result of Filter A, to maintain similar resonance.

After optimal search using EM simulations, the ratio *τ* is found to be 0.8479. It is noted that in this process, the compensated microstrip line is utilized and it is cooptimized with the ratio parameter *τ*. Results show the optimized characteristic impedance for the compensated microstrip line is 33.35  $\Omega$ . The layout shows a half vertex angle of  $\alpha$ =10.93° with a horizontal angle of *β*=23.08°, as compared with the calculations from Eqns. (3) and (4) being *α*=10.93° and *β*=23.07°. The layout indicates that the filter has a footprint of  $30.307 \times 31.170$  mm<sup>2</sup>, meaning the longitude is reduced with a slightly increased lateral size, thus a decreased footprint as compared to the prototype Filter A. Figure 2 shows the layout of this filter, also having 9 slots under a compensated microstrip line.



**Fig. 2.** Layout of the studied zig-zag prototype Filter B, where the grey is the slotline DGS on the metal ground plane, the slanting shadow is the strip on the front side, and the substrate is not shown here for simplicity.

# *3.2 Prototype filter C: Flexible design with high figure-of-merit*

Studies show that the longitude can achieve a minimum when a maximum horizontal periodicity ratio *τ<sup>p</sup>* occurs, that is to say,  $\tau_p$  approaches 1. Hence for this demonstration, we set the initial parameters as  $\tau_p=1$ ,  $\tau_h$ =0.85,  $h_1$ =3.8 mm, and  $p$ =2.5 mm for all periodicity dimensions as a result of  $\tau_p=1$ . Notice that only parameter  $\tau_h$  is searched in the optimal process for timeefficiency considerations, while the characteristic impedance of the compensation line is also 33.35 Ω in this design. An optimal value of *τh*=0.8349 is determined after full-wave EM numerical calculations.

Results show that the layout has an exponential contour along the longitude because of a fixed *τ<sup>p</sup>* of 1. By curve-fitting the data of vertexes, one can find a trajectory expression given by

$$
y = 3.8e^{0.07x} \tag{13}
$$

Shown in Fig. 3 is the filter layout of this flexible design that has a footprint of  $22.35 \times 31.524$  mm<sup>2</sup>. It is seen that each slot has different vertex and horizontal angles  $\alpha_n$  and  $\beta_n$  that can be evaluated from Eqns. (3) and (4). Owing to the increased height *h<sup>n</sup>* under a fixed longitudinal periodicity dimension *p*, the vertex angle *α<sup>n</sup>* would keep reducing and go smaller and smaller but on the contrary, the horizontal angle  $\beta_n$  could keep increasing (becoming larger) as the slot number

increases. In this design, 9 slots are selected for comparison purposes referring to the prototype Filters A and B.



**Fig. 3.** Layout of the prototype Filter C with maximized horizontal periodicity ratio  $\tau_p=1$ , where exponential contour along the longitude is found.

## **4 Experimental demonstrations and discussions on the prototype filters B and C**

The optimally developed Filters B and C are further built for performance demonstrations. Figure 4 shows the photographs of the fabricated demonstrators. For filter B, Fig. 5 shows the measured and simulated S parame-ters. Measurements indicate that the 3 dB cutoff frequency is shifted to 1.965 GHz as compared with the simulated one for 2.04 GHz. The in-band insertion loss is, in general, less than 1.3 dB up to 1.5 GHz, while the suppression band is from 2.65 GHz to 26.4 GHz with an attenuation level over 20 dB. Thus, the demonstrator shows a wide stopband with high suppression levels.

The simulated and measured S parameters of the prototype Filter C are shown in Fig. 6. It is found that the simulated 3 dB cut-off frequency is 2.22 GHz while the measured one is 2.035 GHz. The in-band insertion loss is about 1 dB up to 1.4 GHz. The filter also characterizes ultra-wideband suppression in which one can see to range from 2.95 GHz to over 26.5 GHz, the suppression levels are 20 dB except for a small peak near 14.5 GHz.

To further characterize the performance of the DGS filters, here a comprehensive index called figure-ofmerit is introduced and studied. It is defined based on:

1) Suppression bandwidth (SBW) related to the 3 dB cut-off frequency of the measured filter, thus it is named normalized suppression bandwidth (NSBW) and given by

$$
NSBW = \frac{SBW}{f_{c\_3dB}}
$$
 (14)

- 2) Suppression index (SI) that is related to the suppression level in the suppression band, for example, if the suppression level is referred to 20 dB, the SI is defined as 2.
- 3) Passband-to-stopband transition skirt (TS) that is referred to the 3 dB cut-off frequency and the concerned attenuation (CA) with its frequency (*fca*), given by

$$
TS = \frac{CA(dB) - 3(dB)}{f_{ca}(GHz) - f_{c,3dB}(GHz)}
$$
(15)

4) Normalized size (NS) that is related to the layout footprint and the operation (cut-off) frequency of a filter, given by

$$
NS = \frac{circuit\ size(length \times width)}{\lambda_g^2} \tag{16}
$$

where  $\lambda_g$  is the guided wavelength referring to the 3dB cut-off frequency of the filter.

5) Layer index (LI) that is related to the PCB layers utilized since some types of DGS are of multi-layer architecture. For a DGS using one PCB layer, the LI is defined as 1.

Finally, the figure-of-merit (FoM) is defined as

$$
FoM = \frac{NSBW \times SI \times TS}{NS \times LI}
$$
 (17)

It is noted that the FoM defined here can be more comprehensive by involving other parameters. For instance, the in-band return loss and/or insertion loss, etc, of such kind of filter.

To quantitatively study the FoM defined above, a comparison between some recently reported DGS LPFs is presented in Table 1. It is seen that the developed Filter B approaches the highest FoM of over  $3.5 \times 10^4$ while it is over  $3.1 \times 10^4$  for Filter C in this work. Both have high FoMs among the listed reports in Table 1. This means our design methodology in this contribution can characterize good comprehensive performance in terms of the filter's electric performance and geometric structure parameters.



 $\qquad \qquad \textbf{(c)} \qquad \qquad \textbf{(d)}$ **Fig. 4.** Photographs of the developed prototype filters: (a) front side and (b) back side of Filter B, (c) front side and (d) back side of Filter C



**Fig. 5.** Simulated and measured S-parameters of the prototype Filter B



**Fig. 6.** Simulated and measured S-parameters of the prototype Filter C

| Refs./<br>Years       | $f_{c_3dB}$<br>(GHz) | Suppr. range<br>(GHz) & level   | Trans. level &<br>frequency | Layout<br>footprint $(mm^2)$ | Substrate<br>parameters                 | LI           | FoM<br>$(x10^4)$ |
|-----------------------|----------------------|---------------------------------|-----------------------------|------------------------------|---|--------------|------------------|
| [3]/2017              | 2.0                  | $2.2 - 6.3$<br>$(a)40$ dB       | 40dB<br>$@2.2 \text{ GHz}$  | $36.8\times24$               | $\varepsilon_r = 4.4$<br>$h = 0.8$ mm   | 1            | $\sim$ 1.2       |
| [4]/2019              | 2.2                  | $2.7 - 12$<br>$(a)50$ dB        | 40dB<br>$@2.65$ GHz         | $100 \times 2.6$             | $\varepsilon_r = 3.8$<br>$h = 0.254$ mm | 3            | $\sim$ 1.4       |
| [5]/2020              | 3.62                 | 4.45-20<br>$@16.6$ dB           | 30dB<br>$@4.64$ GHz         | $14.85\times18.4$            | $\varepsilon_r = 9.6$<br>$h = 0.8$ mm   | 1            | ~10.40           |
| [7]/2020              | 1.96                 | $2.61 - 26.5$<br>$(a)20$ dB     | 40dB<br>$@2.74$ GHz         | 40.653×29.546                | $\varepsilon_r = 9.6$<br>$h = 0.8$ mm   | $\mathbf{1}$ | ~2.1             |
| [11]/2020             | 2.11                 | $2.27 - 20$<br>$@18$ dB         | 20dB<br>$@2.57$ GHz         | $15.5 \times 12.7$           | $\varepsilon_r = 4.4$<br>$h = 0.8$ mm   | $\mathbf{1}$ | ~1.4             |
| This work<br>Filter B | 1.965                | $2.65 - 26.4$<br>$\omega$ 20 dB | 40dB<br>$@2.75$ GHz         | 30.307×31.17                 | $\varepsilon_r = 9.6$<br>$h = 0.8$ mm   | $\mathbf{1}$ | $\sim 3.5$       |
| This work<br>Filter C | 2.035                | 2.95-26.5<br>$(a)20$ dB         | 40dB<br>$@3.085$ GHz        | 22.35×31.524                 | $\varepsilon_r = 9.6$<br>$h = 0.8$ mm   | $\mathbf{1}$ | ~23.1            |

**Table 1.** Performance comparison of some reported DGS filters and our study in this work

### **5. Conclusion**

The slotline based zig-zag DGS for microstrip filter designs has been detailed in this study. By optimally determining a few (one or two) key parameters, DGS LPFs with good comprehensive performance can be achieved and based on this design methodology, the developed filters characterize sharp transition shirt, wide suppression band and high suppression levels as well as compact footprint. To further characterize this kind of filters, a comprehensive index called figure-of-merit (FoM) has been studied and defined, and high FoMs are demonstrated in this study for the proposed filters.

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